

# Reimagining Assistive Devices to help Children with Cerebral Palsy (CP) Communicate

Serkan Ekenel 3160660 Jules Goss & Daniel Rossi INDS-4006-002 ID Major Design Project 2 13 April 2021



The ability to **communicate thoughts**, **feelings** and **information** is **essential** to the well-being of a child and their family. Many children with CP have **challenges communicating with speech** and too often it is **assumed** that a child who does not speak is **unable** to connect with or **understand** the **world** around them.

With appropriate **materials** and **focused activities** (interventions) the child with CP can become more able to communicate **thoughts and feelings** and eventually learn how to better **process** these **emotions** in a safe and non-stressful environment. One major problem facing families and therapists is that the children with CP have **unique** sets of abilities and **challenges** which **limits** their ability to **function** in general.

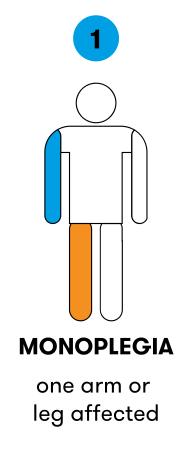
#### WHAT IS CEREBRAL PALSY?

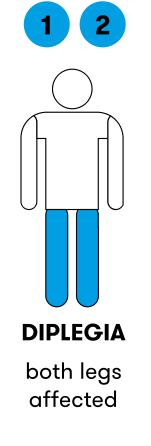


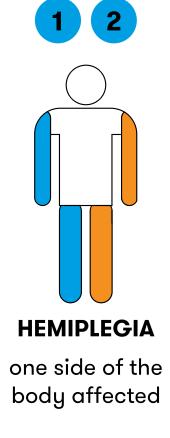
CP is a group of disorders that affect a person's ability to move and maintain balance and posture.



#### **PARTS of the BODY**











**USER GROUP** 

cerebral palsy can affect different parts of the body

#### **PARTS of the BODY**

About 75%-85% children with CP have spasticity (i.e. tightness of, or inability to control muscles).





#### **ASSOCIATED IMPAIRMENTS**



1 in 4 is unable to walk



1 in 4 is unable to talk



3 in 4 experience pain



1 in 4 has epilepsy



1 in 4
has a behaviour
problem



1 in 2
has an intellectual
disability



1 in 10 has severe vision impairment



1 in 4
has bladder control
problems



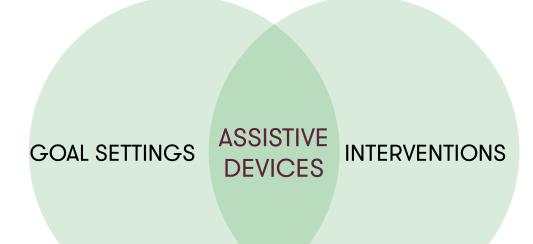
has a sleep disorder



1 in 4
has saliva control
problems



children with CP may also have a range of physical and cognitive impairments



#### **GOAL SETTINGS**

INDEPENDENCE
FUTURE EMPLOYMENT
COMMUNICATION
ACTIVITY OF DAILY LIVING
MOBILITY

#### **ASSISTIVE DEVICES**

AUGMENTATIVE AND ALTERNATIVE COMMUNICATION (AAC) devices, systems, strategies and tools that replace or support natural speech for persons who have difficulties communicating vocally.

#### **INTERVENTIONS**

PHYSIOTHERAPY
SPEECH THERAPY
OCCUPATIONAL THERAPY
MUSIC THERAPY
ART THERAPY
HIPPOTHERAPY



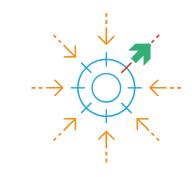
Assistive Devices can provide a catalyst to achieve goals through intervention.

The aim of this research is to find out more about how non-speaking children with CP socialise and communicate in their daily life.









# Primary Research Methods

Empirical Data: Observation

Semi-structured Interviews w/SMEs

# **Subject Matter**

Non-Verbal Children with CP
Parents / Caregivers
Subject Matter Experts

### **Research Focus**

Communication & Activities



# **Empirical Data Summary**

**Retro Fitted ACC Tools** 

Attractive assistive devices that appeal to a child's senses.

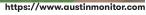
**Lack of Focus** 

Intuitive and easy to use thus encourging independent activity.

**Varied Student Abilities** 

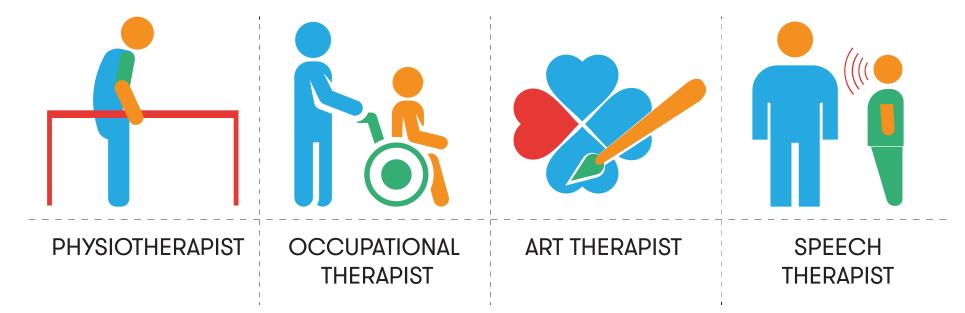
Tailored to each child's ability level.







# **Subject Matter Expert Interviews**



# **Secondary Research Methods:**

Set of Questions Oral and Written Responses Snowball Sampling Method

## **Research Focus**

Daily Communication & Activities



# **SMEs Interviews Summary**

Adapt Therapy to Child's Interests & Needs Talk to parents and therapists as well as personal interaction.

Autonomy/Respect for Their Dignity

Stigma free Assistive Communication Devices can be used by all children

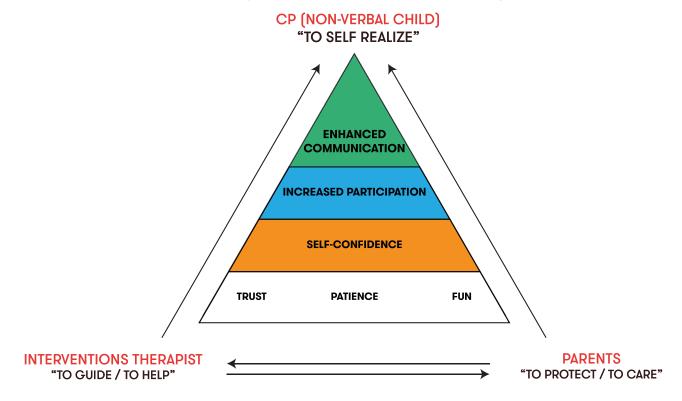
Be Patient as the Child Processes Information Children with DDs may require more processing time.







The users of the product must include not only the children with CP who will use it to achive goals for rehabilitation purposes, but also the stakeholders who will play an important role in facilitating the child's use of the product.

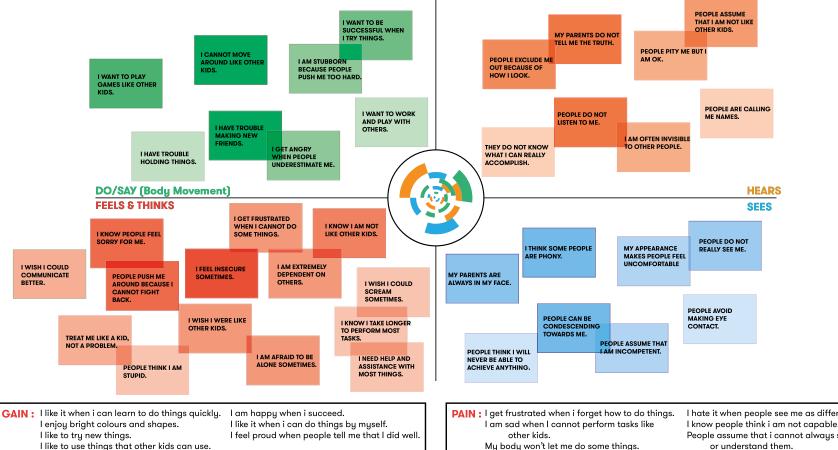


#### PROGRESS SIGNIFICANTLY CORRELATED WITH PARTICIPATION



I believe that if I can change one aspect daily life it will assist them and their care-givers and allow them to move forward in other areas. Small steps will lead to bigger and better results overall.

#### NON-SPEAKING CHILDREN (BOYS/GIRLS) AGED 4-16, WITH PHYSICAL AND MENTAL DISABILITIES.



GOAL:

My body won't let me do some things.

I hate it when people see me as different. I know people think i am not capable. People assume that i cannot always see, hear



- INTUITIVE TO USE, FUN AND ENGAGING.
- SELF-CONFIDENCE INCREASES PARTICIPATION AND ENCOURAGES SOCIAL COMMUNICATIONS



My aim is to design and create a learning tool that will stimulate eye-hand coordination, improve fine motor skills and enhance communication skills for non-Speaking children, aged 4 to 14, with CP. With this tool, it is hoped that children will participate more actively, act independently and improve their self-confidence and self-esteem.









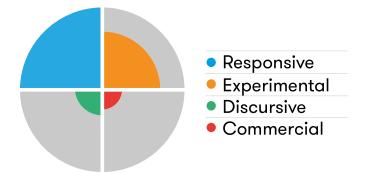








For use in Intensive Support Programs (ISPs) with classroom students who have behavioral, communication, intellectual, or physical needs.



Because it is aimed to be highly personalized and adaptive device it is difficult to envision mass production or significant commercial gain.



#### What is Out There?



Dynavox **\$5000 +** 



32 Message Communicator \$399



PCS™ ThinLine: Set 1 \$150 ( PC/MAC not included)



4 Plate Communicator Say It Play It \$165



iPad Speech only Case (software and ipad are not included) \$500



many AAC devices are not mass produced and are often very expensive

In order to provide a low cost and simple communication board to replace expensive tablets or confusing picture cards, I am going to make a more flexible, child centered communication device that will encourage independent decision making.









By creating objects that appear to be toys or games that have universal application, it is hoped that the child with CP would find these attractive and worthy of their curiosity.

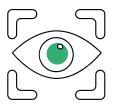
### **Phase of Development**











**SKETCHING** 

**PROTOTYPING** 

3D RENDERING

**3D PRINTING** 

TEST & FEEDBACK

MUST HAVE Adaptable to different physical and intellectual levels. Affordable.

Attractive and child frienly to encourage participation.

Portable and light weight to be used on different surfaces.

COULD

Some IOT entegration

Multi sensory applications such as, sight-sound-touch.
Attractive game like qualities.

SHOULD HAVE

Intiutive to use.

Be sizable and modular.

Should coordinate with learning objectives.

Easily and safely stored when not in use.

WON'T HAVE It won't be very expensive.

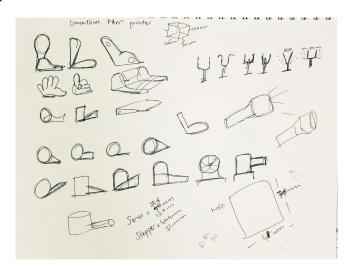
It won't be obsolete after one use.

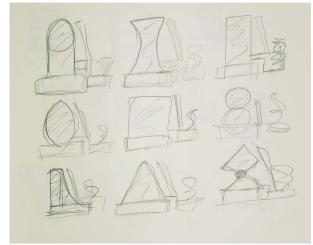
It wont't be complex to use.

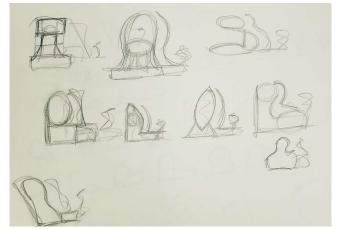
It won't be high tech

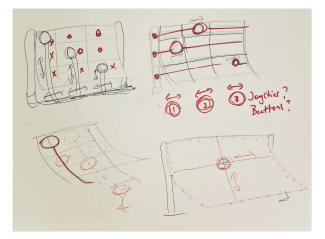


# **Sketches**





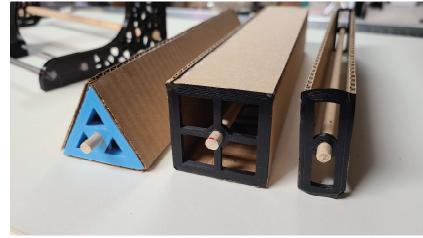






# **Prototype Testing**







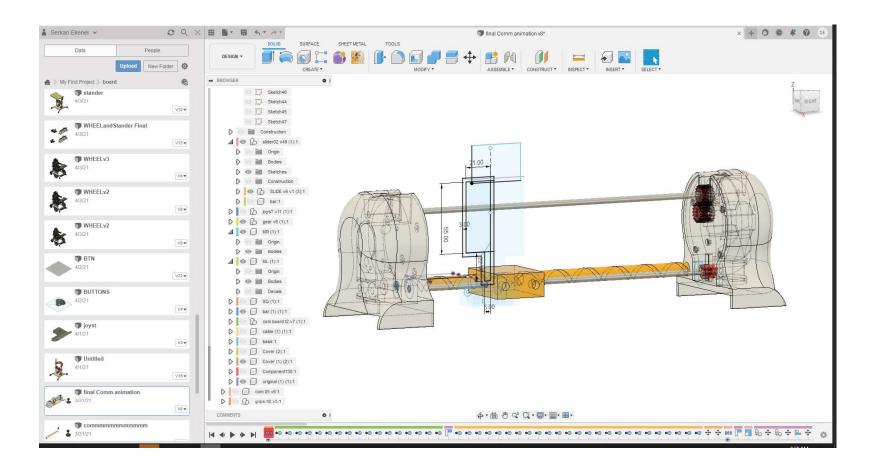








# FUSION 360 Parametric Sketch & Modelling





**Forms** 

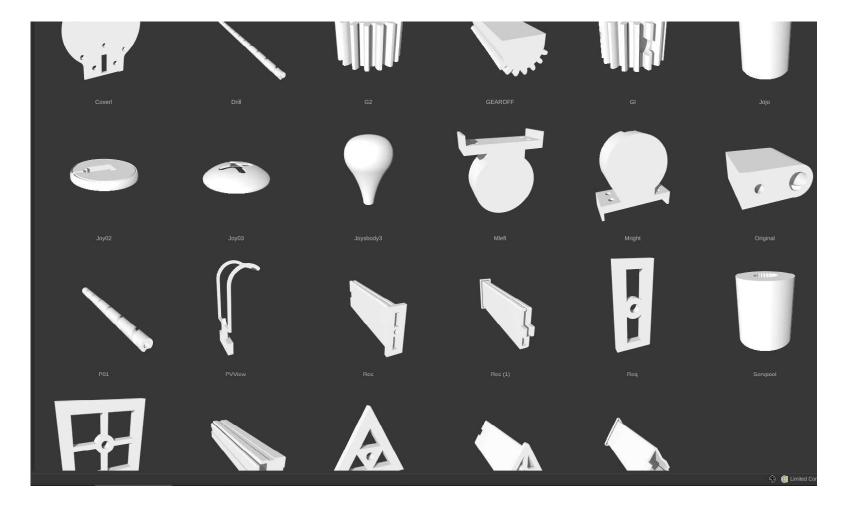








# **3D Printed Parts**

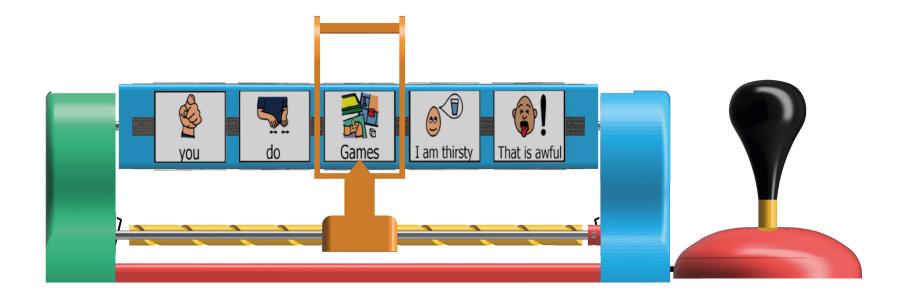






https://www.youtube.com/watch?v=9gl12eyVrSI&t=2s



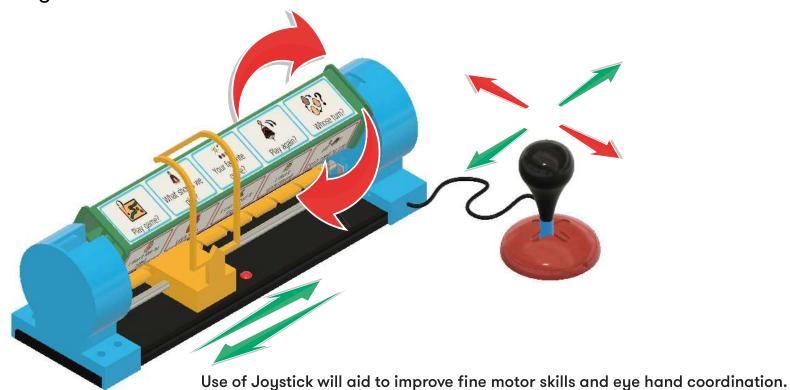


Glide is a highly personalised multi-activity platform geared to the individual needs and abilities of non-Speaking children with CP in a classroom setting.



### **Active Participation:**

Device requires active participation and involvement, while encouraging increased cognition and fine motor skills.





#### Tailored to specific needs and abilities:





#### Adaptable Accessories for Wheelchair and Vertical Standers:

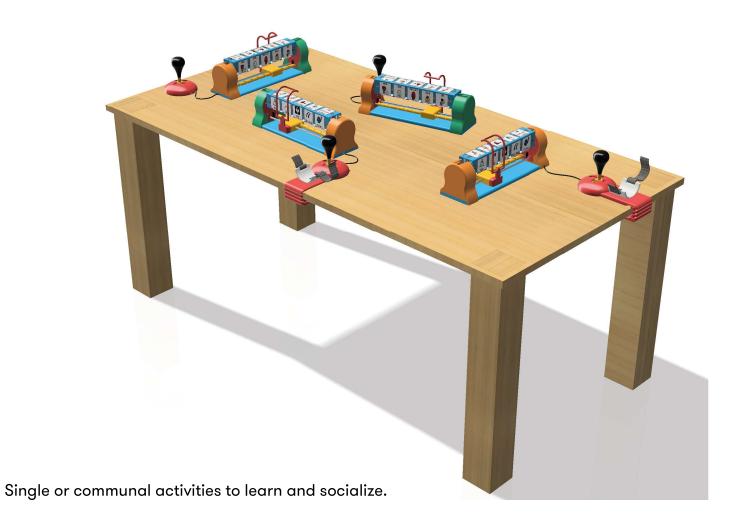
Adaptability and accessibility is a key issue need to be addressed. Understanding child's physical abilities and their body posture will successfuly help child to engage with the product.





Placement on a Wheelchair or Vertical Standing Tray for individual activities.

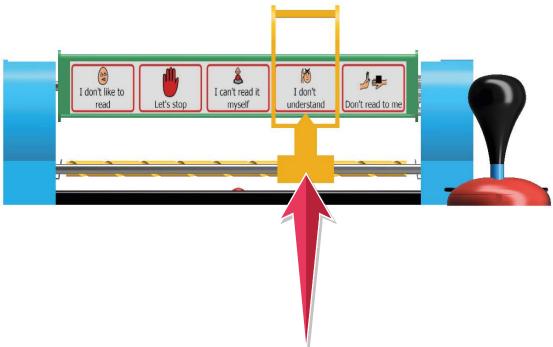
# **Encourages Socializing:**





### **Continuous Highlight Feature:**

Child's choice remains static until the message has been received eliminating potential miscommunication and encouraging independent decision making.

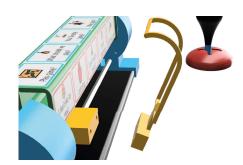




After navigating the VIEW FINDER the selected message does not change until the child moves the Joystick.

#### Multi-activity Platform:

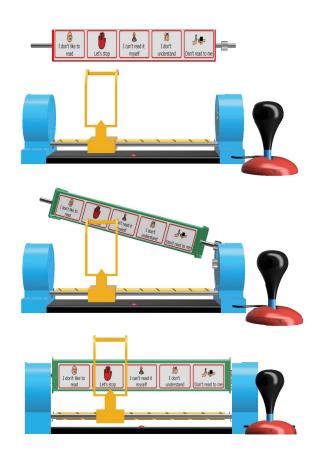
Can be used as a Game Board, Communication device, Mathematics teaching tool, and Vocabulary builder while also enhancing sensory and fine motor skills.



Removable View Finder adapts to each child and can be magnified for the vision impaired.

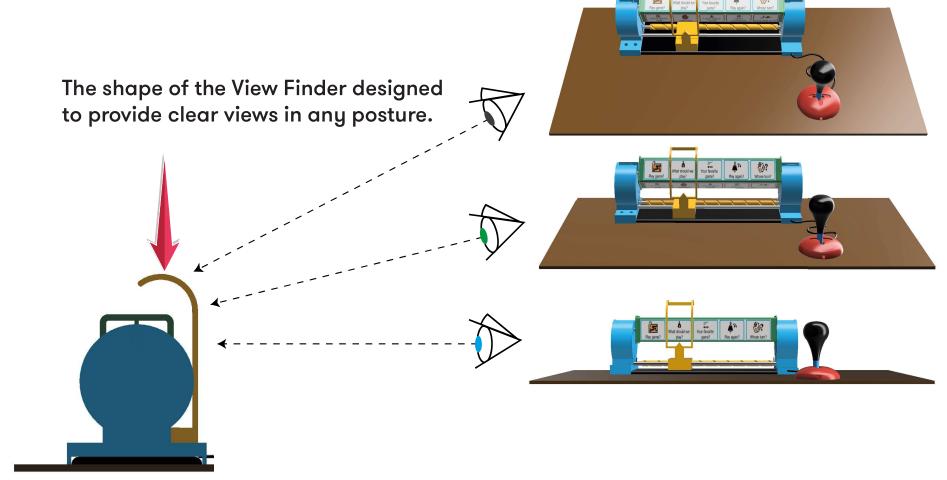


Limit Switch and View Finder Lights to help child with sensory stimuli.



Easily swappable Blocks to prepare activities.



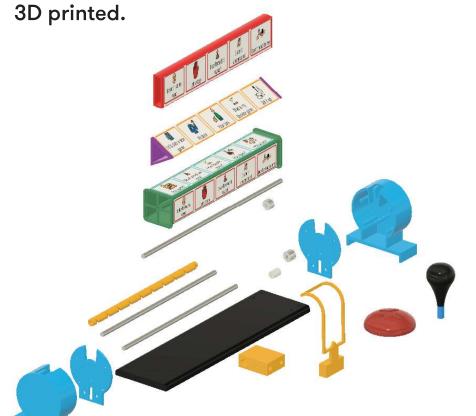




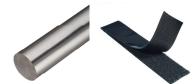
Blocks turns in 5 Degree increments and provides a clear vantage point from child's sitting/standing position

# **Assembly**

Most of the parts are 3D Printed. Parts are designed to be easily 3D printed so not much work needed to assemble after



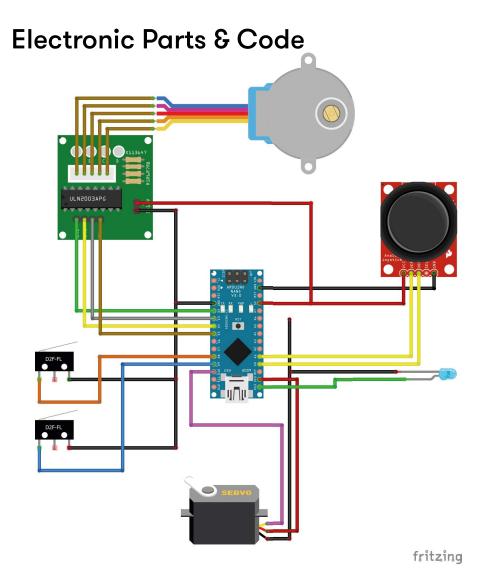




AFFORDABLE AND EASILY AVAILABLE MATERIALS
Ardruino Uno
Stepper Motor
Servo Motor
5/8" Steel Round Rod
Velcro

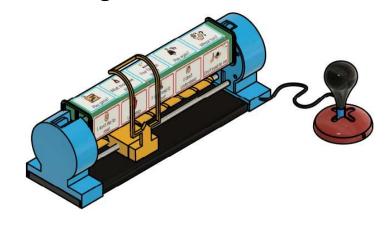


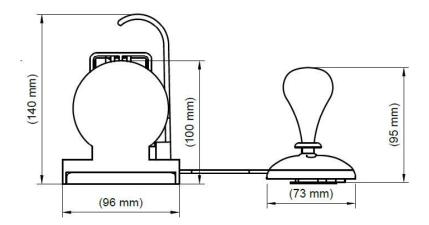


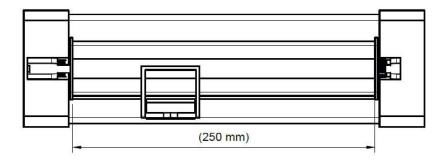


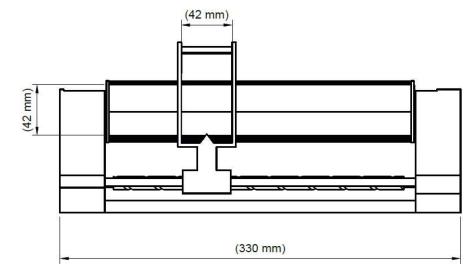
```
//STEPPER MOVEMENT
Controlling a servo position using a potentiometer (variable resistor) by Michal Rinott <a href="http://people.interaction-ivrea.it/m.rinott">http://people.interaction-ivrea.it/m.rinott</a>
                                                                                                                                                                                 Serial.print(" | Y = ");
Serial.print(analogRead(yPin));
  modified on 8 Nov 2013
 by Scott Fitzgerald
http://www.arduino.cc/en/Tutorial/Knob
                                                                                                                                                                        potState = analogRead(A1); //reads the values from the potentiometers
#include <Servo.h>
#include <Stepper.h>
                                                                                                                                                                          Serial.println(potState); // sends joystick data to serial port for debuging
 #define STEPS 64
                                                                                                                                                                        if (potState > 600){ //all code below controls movement down stepper.step(STEPS);
 #define IN2 3
 #define N3 4
#define N4 5
                                                                                                                                                                        if (potState < 200){
stepper.step(-STEPS);
 Stepper stepper(STEPS, IN1, IN3, IN2, IN4); // stepper motor sequence 1-3-2-4
                                                                                                                                                                        //LIMIT_SWITCH 01
 int potState = 0:
int stepperS = 520;
int backSW = 300;
                                                                                                                                                                          if( (digita|Read(Lswitch1) == LOW) && (flag == 0) )
                                                                                                                                                                          Serial printin("L1 is closed");
 Servo servo; // create servo object to control a servo
 int vPin = A1: //X-axis attach to A0
 int yValue; //intialiaze a varibale to save the data from the X-axis from the joystick
int joypin1 = A0; // analog pin used to connect the joystick int val; // variable to read the value from the analog pin
                                                                                                                                                                          if( (digitalRead(Lswitch1) == HIGH) && (flag == 1) )
                                                                                                                                                                           SeriaLprintin("L1 is opened");
// global variables (constants) to represent direction of servo rotation const int COUNTER_CLOCKWISE = 1000; const int STOPEDE = 1500; const int CLOCKWISE = 2000; //limitSwitch
                                                                                                                                                                        if ( flag == 0 )
                                                                                                                                                                         {
servo.writeMicroseconds(STOPPED);
delay(1000); // allow to rotate for 5 seconds
// servo.writeMicroseconds(COUNTEC,CLOCKWISE);
// delay(1000)/ allow to rotate for 5 seconds
servo.writeMicroseconds(CLOCKWISE); // stop rotation
 int Lswitch1 = 8;
 int Lswitch2 = 9:
int flag = 0;
int flag2 = 0;
                                                                                                                                                                          delay(150);
int led = 13:
                                                                                                                                                                         digita Write(Lswitch1, HIGH):
 void setup() {
  Serial begin(9600);
servo.attach(10); // attaches the servo on pin 9 to the servo object
pinMode(Lswitch), INPUT);
pinMode(Lswitch2, INPUT);
                                                                                                                                                                       //LIMIT_SWTCH 02
if( (digita|Read(Lswitch2) == LOW) && (flag2 == 0) )
  pinMode(led, INPUT);
                                                                                                                                                                      Serial println("L2 is closed");
flag2 = 1;
delay(20);
void loop() {
                                                                                                                                                                          if( (digita|Read(Lswitch2) == H|GH) && (flag2 == 1) )
 Serial print("X = "\
Serial.print( A = 7,
Serial.print(analogRead(val));
delay(20);
                                                                                                                                                                          SeriaLprintIn("L2 is opened");
                                                                                                                                                                      flag2 = 0;
delay(20);
//SERVO MOVEMENT val = analog(Read[pypin1); // reads the value of the potentiometer (value between 0 and 1023) val = map(val, 0, 1023, 0, 180); // scale it to use it with the servo (value between 0 and 180)
                                                                                                                                                                         if ( flag2 == 0 )
  servo.write(val);
delay(15);
                                       // sets the servo position according to the scaled value
                                    // waits for the servo to get there
                                                                                                                                                                          servo.writeMicroseconds(STOPPED);
delay(1000); // allow to rotate for 5 seconds
                                                                                                                                                                       oray (100);// allow to rotate for 5 seconds
servo-writeMicroseconds/COUNTER_CLOCKWISE);
delay(150);// allow to rotate for 5 seconds
// servo-writeMicroseconds/CLOCKWISE);// stop rotation
// delay(100);
  if (analogRead(val) < 499 && analogRead(val) > 480)
{digita|Write(|ed, HIGH);}
     {digitalWrite(led, LOW);}
                                                                                                                                                                         digita Write(Lswitch2, HIGH);
```

# Drawing

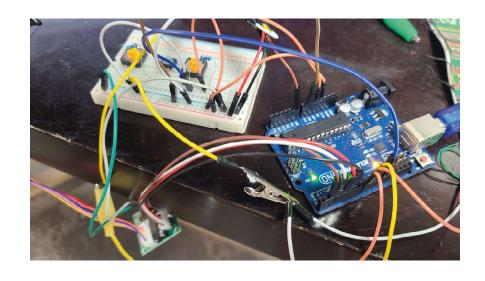


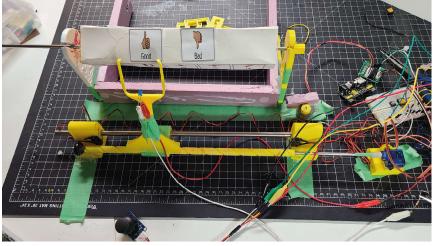


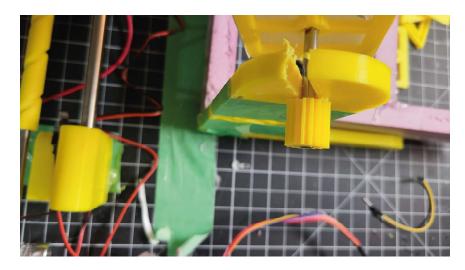


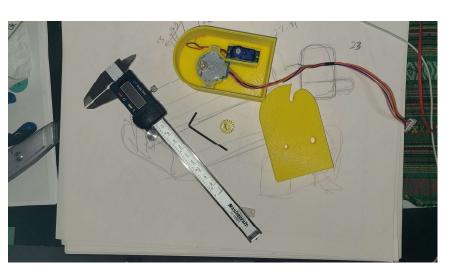




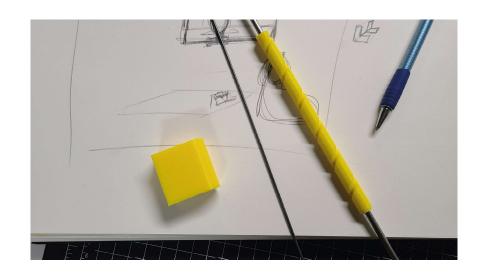


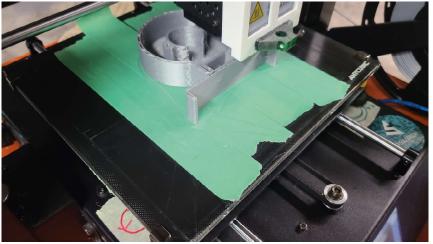


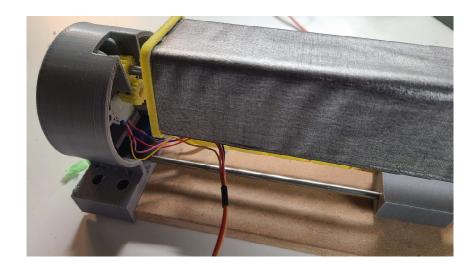






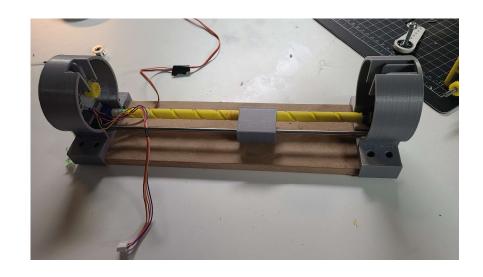
















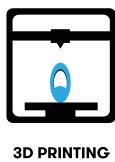


https://www.youtube.com/watch?v=5tMFQ6fO2eg









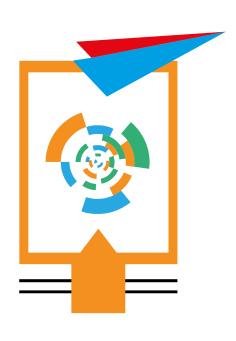
**COMMUNITY** 

Strategic partners include, but are not limited to, School Boards, hospitals, special needs teachers, classroom assistants, parents and other caregivers who are directly involved with children exhibiting moderate-to-severe forms of Cerebral Palsy.

By canvasing the 3D Printing community on Social Media I hope to find volunteers who will print parts for my platforms.







for all your help, thank you !!!